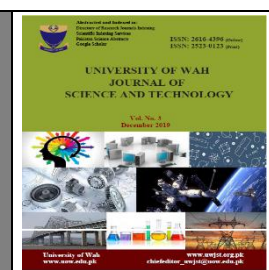




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A Smarter Energy Management System for Lithium-ion Battery and Super Capacitor Based Hybrid Energy Storage System

Muhammad Umair Ali, Sadam Hussain, Sarvar Hussain Nengroo and Hee-Je Kim

Abstract— The electrical energy storage system is still the tailback for the commercialization of many electrical appliances. The battery storage system (BSS) has a high energy density but lower power density, and vice versa in case of the super capacitor storage system (SCSS). In this work, a hybrid energy storage system (H-ESS) with smart energy management system (EMS) is designed. The proposed EMS is based upon fuzzy logic that controller smartly distribute the power between BSS and SCSS depending upon the state of charge (SOC). This technique reduces the stress (high value current) of BSS during the challenging condition to prolong its life. The methodology is simulated on MATLAB™ Simulink 2019. The simulation and comparative analysis with other EMS techniques have been carried out and the results showed that the smart EMS reduces almost 17% stress on BSS. This technique can be used to design EMS for other electrical appliances such as electric vehicles, electric wheelchairs, smart grid system, etc.

Index Terms— Hybrid energy storage system (H-ESS), energy management system (EMS), fuzzy logic controller, and state of charge (SOC).

I. INTRODUCTION

The need for electrical energy is increasing exponentially in the last few years, and it conduces to steadily increase in the future due to growth in population and economy [1-3]. According to a report, the annual energy demand of the world will increase 35% at the end of 2040 [4]. Now a days, fossil fuels are the foremost source of electrical power generation and transportation. However, the use of fossil fuels will reduce due to climate effects, high prices, and depletion of crude oils. To

surmount these concerns, progress in technology has yielded diverse liberties of generating energy using renewable energy (RE) sources [5-6]. In the transportation industry, electric vehicles (EVs) are developed to reduce environmental pollution and energy crisis concerns of the conventional vehicle [7]. In 2018, according to a report, the generation of electrical energy from RE and fossil fuels sources will be equal [8]. The RE sources are episodal, so RE and EVs also require energy system to store electrical energy [9]. There are two main categories of the electrical energy storage system (ESS): (i) Batteries storage system (BSS) and (ii) Super capacitor storage system (SCSS) [7].

There are various types of BSS, reported in the literature such as lithium-ion (LI), zinc-bromine flow (ZBF), vanadium redox flow (VRF), nickel-cadmium (NiCd), sodium nickel chloride (NaNiCl), sodium sulphur (NaS), and lead-acid (LA) [10]. The comparison of the various properties of BSS is presented in Fig. 1, which shows that the lithium ion battery storage system (LIBSS) has the best energy and power density, better life cycle, and reasonable cost [9, 10]. On the other hand, the SCSS has the energy and power density in the range of 4–14 Wh/L and 3000–40000 W/kg, respectively [11]. The charging and discharging time of SCSS is almost 20 times lesser than the LIBSS. The LIBSS and SCSS are compared in Table I.

Table I shows that the SCSS has very high-power density and LIBSS has very high energy-density. In EVs, the high current value is needed during uphill climbing and in high acceleration mode, which degraded the LIBSS resulting in the shorting the life span of LIBSS. The combination of LIBSS and SCSS can be utilized to tackle these challenging working conditions in EVs as well as in smart grids [12]. This combination of LIBSS and SCSS is also known as hybrid-ESS (H-ESS). Besides it, an energy management system (EMS) is needed to smartly exploit the properties (high power density of SCSS and high energy density of LIBSS) of H-ESS. The main working of smart EMS is to reduce the stress (high value current) on the

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LIBSS during high demanding conditions [13].

In a study [14], the H-ESS has been categorized into three different categories (i.e passive H-ESS, semi active H-ESS, and fully active H-ESS) based upon working. Wavelet-fuzzy logic controller to design an EMS was based on the frequency decoupling method was utilized in [15]. In passive H-ESS, the LIBSS and SCSS can be easily coupled directly without using any converter [16]. The passive H-ESS is very cheap at the loss of the system's uncontrollability, whereas the semi-active H-ESS is the tradeoff between the performance and the cost. In semi active H-ESS, one converter is used to partially control the H-ESS. It can only control the output power of a single ESS (LIBSS or SCSS). The fuzzy logic controller to charge the LIBSS was utilized and a rule base EMS was designed to draw the discharging current for an electric wheelchair in [17]. The complete controllability of the power utilization of H-ESS is the main drawback of semiactive strategy. The fully active H-ESS addressed the controllability issues of the passive H-ESS [18]. Dual active bridge based converter were also proposed to control the H-ESS [19]. However, the fully active H-ESS has the complete control of H-ESS, it increases the complexity of the system [14]. To address this issue, a smart and simple controller is required for smart distribution of currents in H-ESS.

In this work, a fuzzy logic-based, fully active H-ESS is proposed to smartly distribute the output current of H-ESS between LIBSS and SCSS depending upon their SOC. The fuzzy logic controller regularly monitors the SOC of the LIBSS and SCSS. The rule-base of the controller is designed in such a way that it can reduce the stress of LIBSS by utilizing the high-power density of SCSS in demanding condition to prolong its life cycle. The MATLABTM Simulink 2019 was used to implement and

verify the smart EMS. The results shows that the proposed system reduces the stress of LIBSS in H-ESS.

II. DESIGN OF SMART EMS

The proposed system consists of LIBSS, bank of SCSS, DC-DC converters, DC bus bar, two SOC measured units, and fuzzy logic based smart EMS, as shown in Fig. 2.

The smart EMS regularly monitors and measures the SOC of SCSS (SOC_{SCSS}) and LIBSS (SOC_{LIBSS}) by using SOC measurement unit. These measured SOC are fed to the smart fuzzy logic-based controller and the fuzzy logic controller generates the PWM signals for the converters, depending upon the fuzzy rule-base in order to find the optimum discharge currents value for both ESSs.

TABLE I
COMPARISON OF LIBSS AND SCSS [11]

Property	LIBSS	SCSS
Energy Density (Wh/L)	200–400	4–14
Power Density (W/kg)	1500	3000–40000
Voltage (V)	3.6–4.3	2.7–3.5
Life Cycle (years)	5–10	10–15

A. Fuzzy Logic Controller Design

Since fuzzy logic controller is bormally simpler, easily implementable, and robust, but it also does not need a mathematical model of the system for its working [20], which make it well suited for anticipating the behavior of any non-linear system. The fuzzy logic controller can easily be categorized as; i) Fuzzifier, ii) Rule base, iii) Inference engine, and iv) Defuzzifier as shown in Fig. 3 [21].

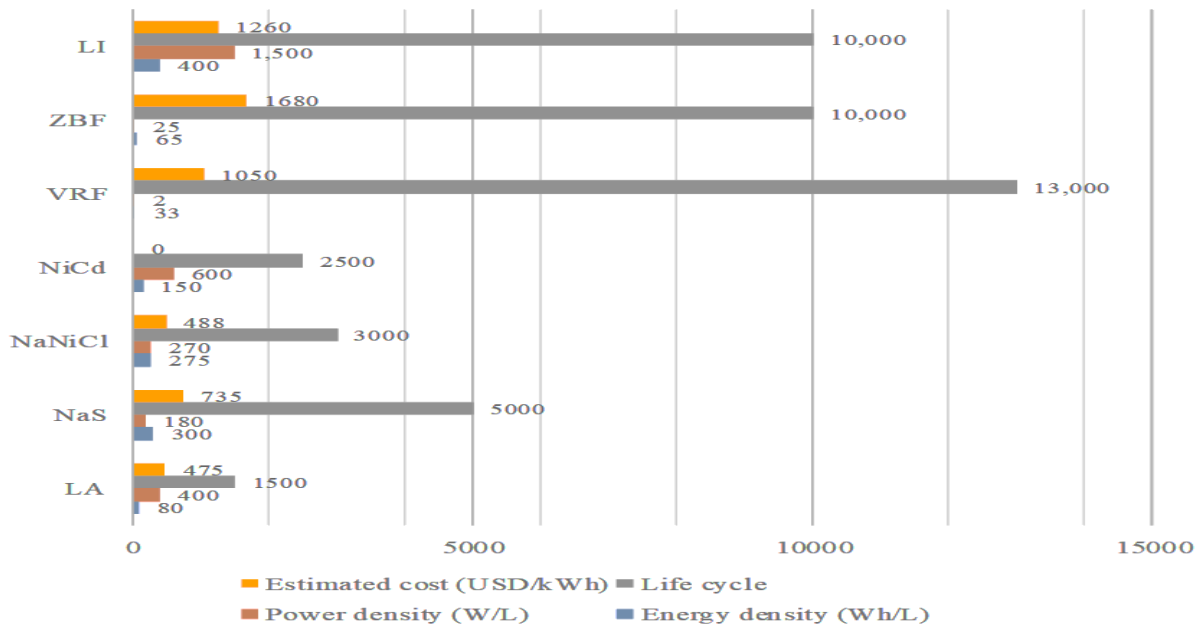


Fig. 1. Properties of various BSS [9, 10].

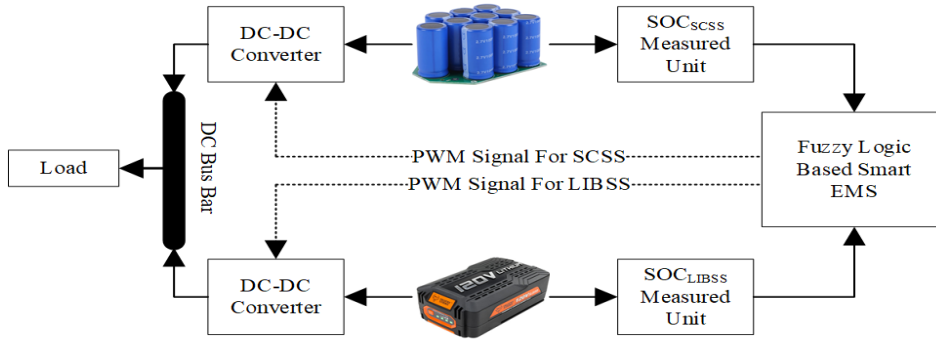


Fig. 2. Schematic diagram of proposed EMS.

Fuzzifier: it changes the input values SOC_{SCSS} and SOC_{LIBSS} into crisp values $a_b(y)$ and $a_d(x)$ using the membership function of linguistic fuzzy sets, respectively. **Rule base:** the main controlling mechanism of the system is stored in the rule base. It needs a lot of expertise to design the rule base of the fuzzy logic controller. The rule-base of the proposed system is listed in Table II and III.

Fuzzy interface engine: it changes the crisp values $a_b(y)$ and $a_d(x)$ into output crisp value $a_i(z)$ using control law saved in the rule-base, as shown in Fig. 3.

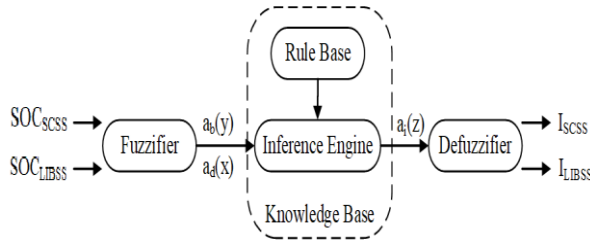


Fig. 3. Overview of fuzzy logic controller.

TABLE II
RULE BASE FUZZY LINGUISTIC VARIABLE FOR LIBSS

		SOC _{LIBSS}				
SOC _{SCSS}	I _{LIBSS}	VL	L	M	H	VH
	VL	VL	M	M	H	VH
	L	VL	L	M	M	H
	M	VL	L	L	M	H
	H	VL	L	L	M	M
	VH	VL	VL	L	M	M

Table II and III list the five rule-base linguistic variables: VL (very low), L (low), M (medium), H (high), and VH (very high).

Defuzzifier: it converted $a_i(z)$ to the true value of LIBSS current and SCSS current (I_{SCSS}) by using the membership function of the proposed fuzzy logic controller.

The conversion of true input values to crisp value and crisp value to output values using the membership function is shown in Fig. 4. The max-min and center of gravity method are used for fuzzification and defuzzification process [22].

TABLE III
RULE BASE FUZZY LINGUISTIC VARIABLE FOR SCSS

		SOC _{LIBSS}				
SOC _{SCSS}	I _{SCSS}	VL	L	M	H	VH
	VL	VL	VL	VL	VL	VL
	L	L	L	VL	VL	VL
	M	M	L	L	VL	VL
	H	H	M	L	L	VL
	VH	VH	H	M	M	L

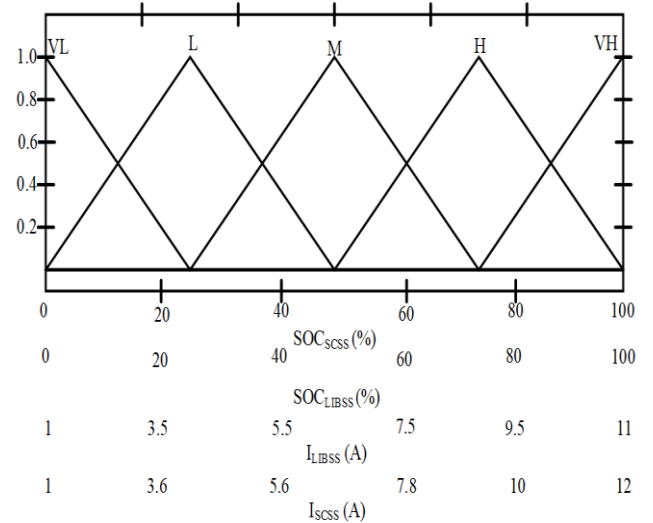


Fig. 4. Values of membership function of proposed fuzzy logic controller for smart EMS.

The 3-dimensional output surfaces of the I_{LIBSS} and I_{SCSS} is shown in Fig. 5a and Fig. 5b.

B. State of Charge (SOC) Estimation

The SOC of the ESS, is interpreted as the proportion of current capacity at any instant to the maximum nominal capacity of the ESS [23]. Several methods can be found in the literature for SOC estimation such as book keeping, model-based, computer intelligence-based, and direct measurement methods [9,24]. In this work, a simple coulomb counting SOC estimation method (a type of book-keeping method) is adopted to find the SOC of both the ESS. The discrete mathematical form of coulomb

counting method can be expressed as follows:

$$SOC^k = SOC^{k-1} - \frac{I_{ESS} T}{\text{Maximum Nominal Capacity}} \quad (1)$$

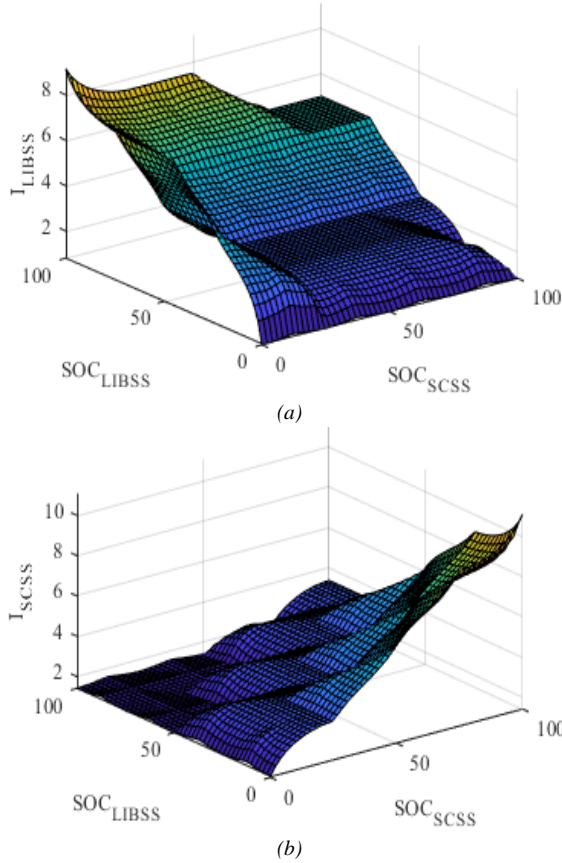


Fig. 5. 3-D surfaces; a) I_{LIBSS} and b) I_{SCSS} .

The SOC^k is the SOC at current time step, I_{ESS} is the current of ESS (I_{ESS} is the I_{LIBSS} and I_{SCSS} in case of LIBSS and SCSS, respectively), and T is the sampling time in equation (1).

III. SIMULATION RESULTS

The MATLABTM Simulink 2019 was used to implement and validate the proposed smart EMS. Firstly, the stored data of LIBSS and SCSS was used to find the SOC of both EMS. The estimated SOC of both ESS was then fed to the fuzzy logic controller. The proposed controller was designed as discussed in Section II. The fuzzy logic controller calculates the optimum values of discharging current of both ESS depending upon SOC. The Simulink model of the proposed system is shown in Fig. 6.

In this work, the only aim is to design a smart controller to minimize the stress of LIBSS, and the power of SCSS is smartly utilized in challenging condition to prolong the lifetime of LIBSS. The designing of the DC-DC converter is not part of this research. The fuzzy logic controller can easily generate the PWM signals for the converters to draw the currents.

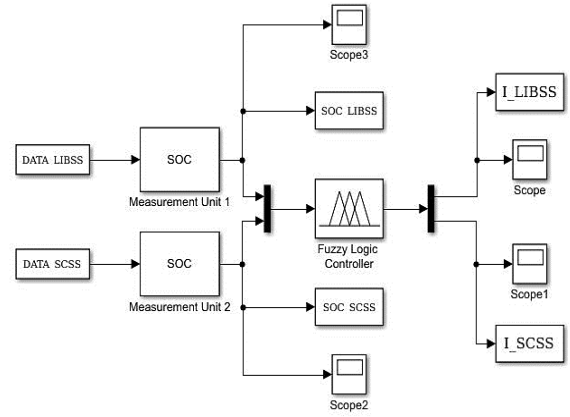
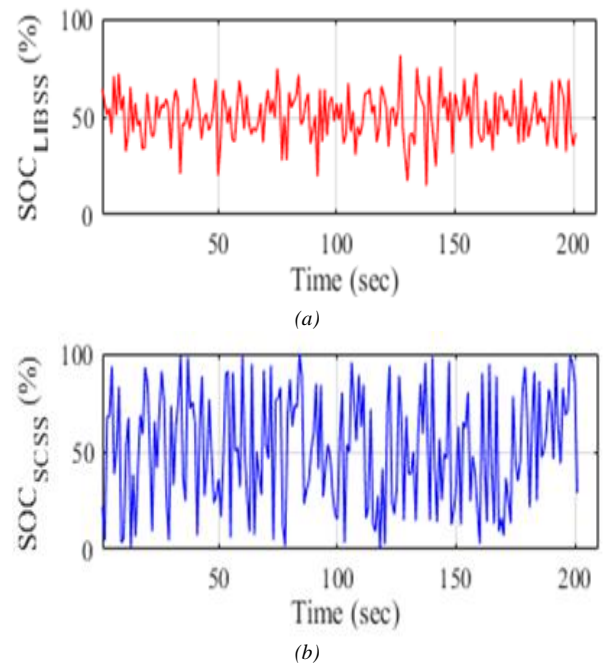


Fig. 6. Simulink model of proposed EMS.

Fig. 7 shows the results of the proposed smart EMS for H-ESS. Fig. 7(a) and Fig. 7(b) show the SOC of LIBSS and SCSS, respectively. Fig. 7(c) and Fig. 7(d) show the current profiles of both ESS types. Fig. 8 compares the current values of proposed and passive H-ESS.

IV. DISCUSSION

In a passive system, the SCSS and LIBSS are connected in parallel without any current control mechanism as discussed in Section I. The passive system is a low-cost ESS, and it has more advantages in contrast to standalone LIBSS. But the issue of uncontrollability of power-sharing between both the ESS cannot be resolved due to direct coupling of LIBSS and SCSS. On the other hand, the proposed fully active system has the capability of full control on both ESS. The fuzzy logic controller based upon the SOC levels is designed to reduce further stress on LIBSS as compared to the passive system.



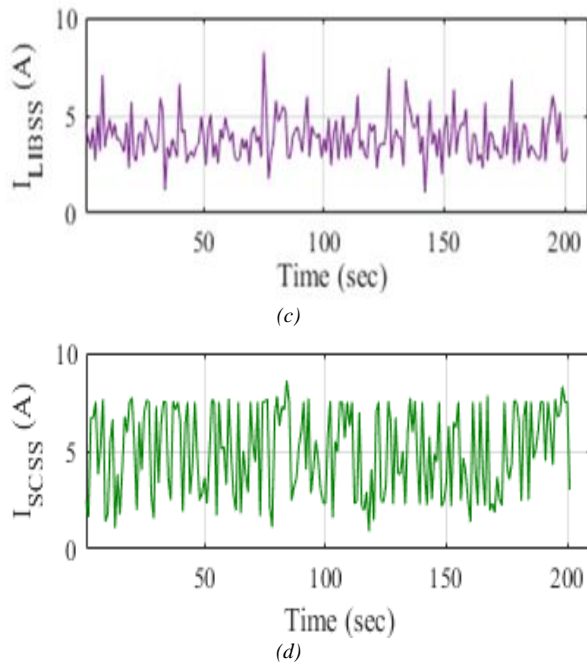


Fig. 7. Simulation results of the proposed EMS; a) SOC_{LIBSS} , b) SOC_{SCSS} , c) I_{LIBSS} and d) I_{SCSS} .

Several simulations were performed to validate the proposed H-ESS under different SOC values of both ESS. The results are also compared with the passive system. The Fig. 7 shows the results of the proposed EMS for H-ESS. The SOC of LIBSS is more stable as compare to SCSS due to high energy density. The basic aim of this research is to reduce the stress of LIBSS by tackling the high current values using the SCSS. It is evident from the Fig. 7, that the proposed controller maintains the current of LIBSS up to a certain limit. The current of SCSS keeps on changing according to the conditions. Low value of SCSS current is discharged during the low demanding condition because it can be easily tackled by LIBSS.

Fig. 8 shows the comparison of the passive and proposed H-ESS, the LIBSS current of the proposed H-ESS is less compared to the passive system. In case of passive system, the values of distribution currents of LIBSS and SCSS mainly depend upon their internal resistances. In this research, it is considered that the internal resistances of both ESS are same. The second plot shows the amount of extra current taken by LIBSS in case of passive system. Similarly, the third graph shows the comparison of SCSS current of both systems. Fourth graph are on negative side, it shows that the proposed EMS smartly utilize the power of SCSS to reduce over burden on LIBSS to prolong its live cycle.

Table IV shows the average current value of both the system for whole cycle. It can be clearly seen that the proposed system took almost 0.7935A lesser average LIBSS current using the proposed technique. The stress of LIBSS is reduced. In future, the proposed system should be checked and implemented in real time application. The SOC estimation accuracy can be improved using advance techniques and quality of sensors [25].

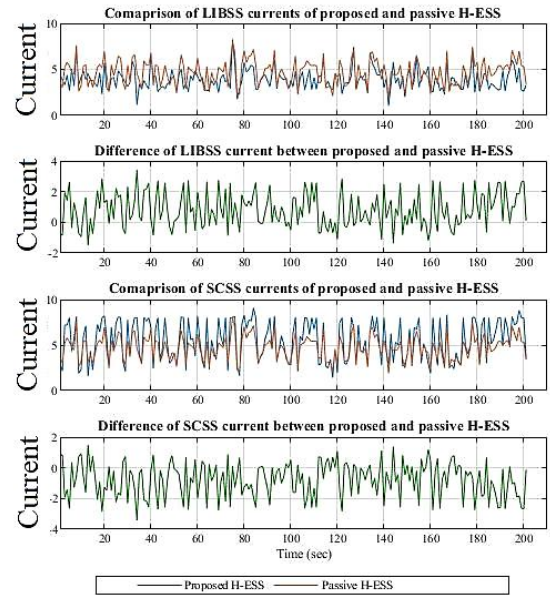


Fig. 8. Comparison of the proposed and passive H-ESS.

TABLE IV
COMPARISON OF PROPOSED AND PASSIVE H-ESS.

Type of H-ESS System	I_{LIBSS} (A)	I_{SCSS} (A)
Proposed	3.8822	5.4692
Passive	4.6757	4.6757

V. CONCLUSION

In this work, a new approach for H-ESS based upon fuzzy logic controller is introduced. The proposed approach separately monitors and measures the SOC of both types of ESS. The SOC of both ESS are fed to the fuzzy logic-based controller. The controller determines the discharge current values of LIBSS and SCSS based upon input SOC. The simulation study is carried out to examine and validate the proposed technique. The simulation and comparative analysis suggests that the proposed algorithm reduces the stress of LIBSS upto 17%. The proposed controller can be easily used to tackle the abrupt changes of current in EVs, smart grids, electric wheelchair, etc. Furthermore, it also protects LIBSS from damages.

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